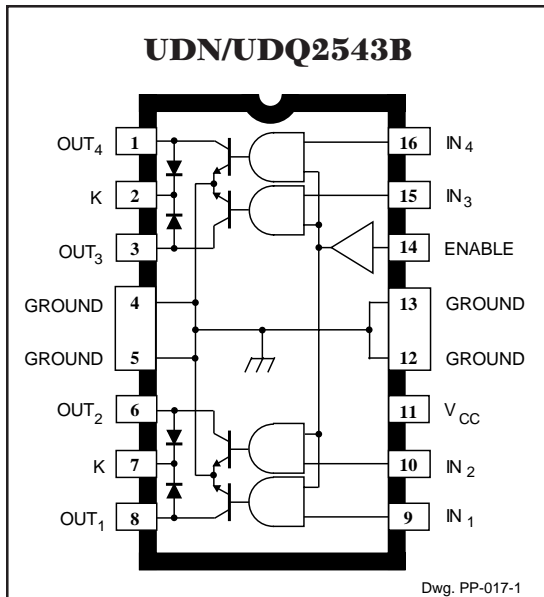


## PROTECTED QUAD POWER DRIVERS



### ABSOLUTE MAXIMUM RATINGS at $T_A = 25^\circ\text{C}$

Output Voltage, $V_{OUT}$ .....	60 V
Over-Current Protected Output Voltage, $V_{OUT}$ .....	25 V
Output Current, $I_{OUT}$ .....	1.0 A*
Supply Voltage, $V_{CC}$ .....	7.0 V
Input Voltage, $V_{IN}$ or $V_{EN}$ .....	18 V
Package Power Dissipation, $P_D$ .....	See Graph
Operating Temperature Range, $T_A$	
(UDN2543B/EB) ....	$-20^\circ\text{C}$ to $+85^\circ\text{C}$
(UDQ2543B/EB) ....	$-40^\circ\text{C}$ to $+85^\circ\text{C}$
Storage Temperature Range, $T_S$ .....	$-55^\circ\text{C}$ to $+150^\circ\text{C}$

\*Outputs are peak current limited at approximately 1.0 A per driver. See Circuit Description and Applications for further information.

Providing interface between low-level logic and power loads to 100 W, the UDx2543B and UDx2543EB quad power drivers combine NAND logic gates and high-current bipolar outputs. Each of the four independent outputs can sink up to 700 mA in the ON state. The outputs have a minimum breakdown voltage (load dump) of 60 V and a sustaining voltage of 35 V. The inputs are compatible with most TTL, DTL, LSTTL, and 5 V CMOS and PMOS logic systems.

Over-current protection has been designed into each channel of the UDx2543B/EB and typically occurs at 1 A. It protects any one channel from output short circuits with supply voltages up to 25 V. When the maximum output current is reached, that output stage is driven linearly. If the over-current condition continues, that output's thermal limiting will operate, limiting that output's power dissipation to approximately 2.4 W. The outputs also include diodes for voltage clamping with inductive loads such as relays, solenoids, or dc stepper motors.

These devices are supplied in a 16-pin power DIP of batwing construction (suffix 'B') to provide for maximum package power dissipation. They are also available in a 28-lead PLCC (suffix 'EB') for surface-mount applications. All devices are rated for continuous operation over the temperature range of  $-20^\circ\text{C}$  to  $+85^\circ\text{C}$  (UDN2543B/EB) or for use in automotive applications over an extended temperature range as the UDQ2543B/EB.

### FEATURES

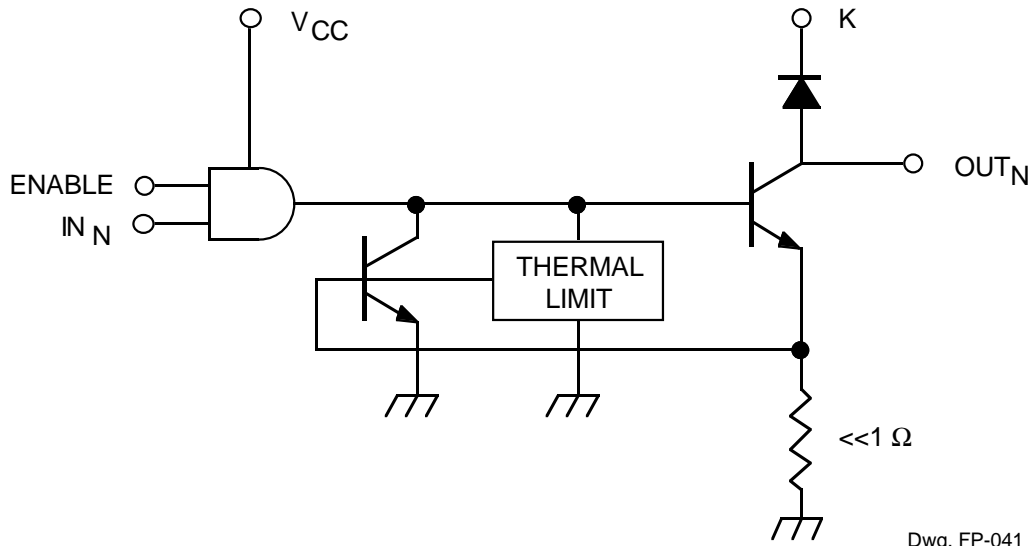
- 700 mA Output Current per Channel
- Low Output-Saturation Voltage
- Integral Output Transient-Suppression Diodes
- TTL, CMOS, PMOS, NMOS Compatible Inputs
- Independent Over-Current Protection for Each Output

Always order by complete part number:

Part Number	Package	Operating Temperature
UDN2543B	16-Pin DIP	$-20^\circ\text{C}$ to $+85^\circ\text{C}$
UDN2543EB	28-Lead PLCC	$-20^\circ\text{C}$ to $+85^\circ\text{C}$
UDQ2543B	16-Pin DIP	$-40^\circ\text{C}$ to $+85^\circ\text{C}$
UDQ2543EB	28-Lead PLCC	$-40^\circ\text{C}$ to $+85^\circ\text{C}$

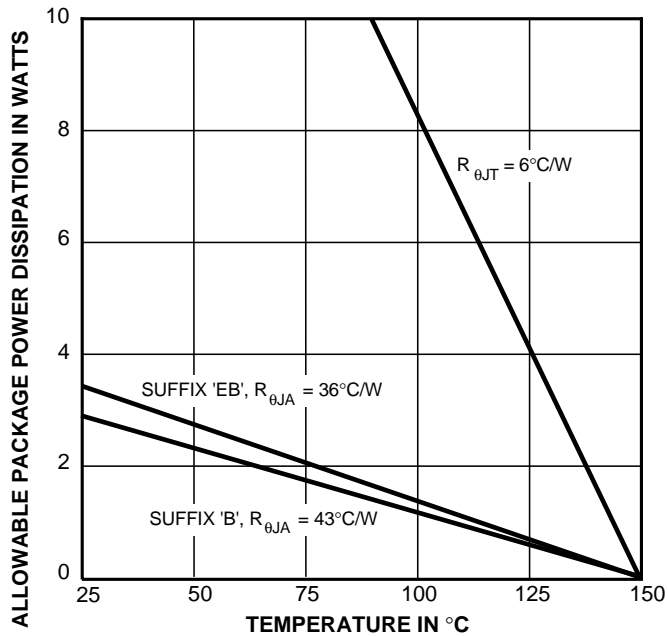
# 2543 PROTECTED QUAD POWER DRIVERS

## FUNCTIONAL BLOCK DIAGRAM (1 OF 4 CHANNELS)



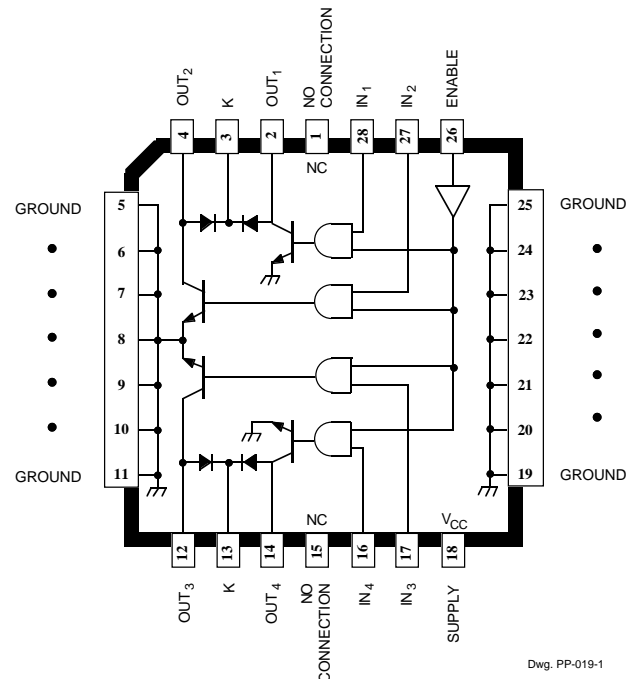
Dwg. FP-041

NOTE: These devices do not include an absolute thermal shutdown. Package power dissipation under fault conditions (2.4 W in the faulted channel) must therefore be evaluated at maximum operating temperature.



Dwg. GP-004-1A

## UDN/UDQ2543EB



Dwg. PP-019-1



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# 2543 PROTECTED QUAD POWER DRIVERS

## ELECTRICAL CHARACTERISTICS at $T_A = +25^\circ\text{C}$ (UDN2543B/EB) or over operating temperature range (UDQ2543B/EB only), $V_{CC} = 4.75\text{ V to }5.25\text{ V}$

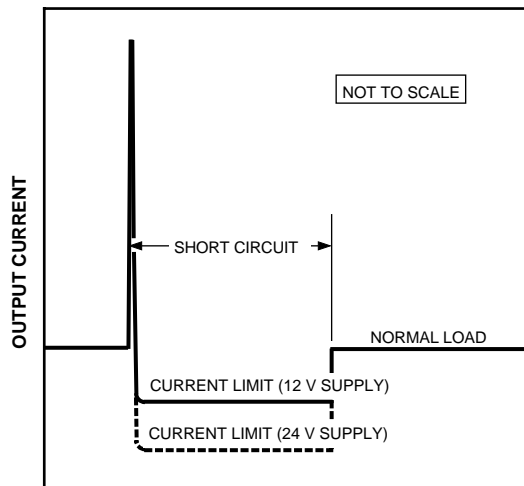
Characteristic	Symbol	Test Conditions	Limits		
			Min.	Max.	Units
Output Leakage Current	$I_{CEX}$	$V_{OUT} = 60\text{ V}, V_{IN} = 0.8\text{ V}, V_{EN} = 2.0\text{ V}$	—	100	$\mu\text{A}$
		$V_{OUT} = 60\text{ V}, V_{IN} = 2.0\text{ V}, V_{EN} = 0.8\text{ V}$	—	100	$\mu\text{A}$
Output Sustaining Voltage	$V_{OUT(SUS)}$	$I_{OUT} = 100\text{ mA}, V_{IN} = V_{EN} = 0.8\text{ V}$	35	—	V
Output Saturation Voltage	$V_{OUT(SAT)}$	$I_{OUT} = 100\text{ mA}, V_{IN} = V_{EN} = 2.0\text{ V}$	—	200	mV
		$I_{OUT} = 400\text{ mA}, V_{IN} = V_{EN} = 2.0\text{ V}$	—	400	mV
		$I_{OUT} = 700\text{ mA}, V_{IN} = V_{EN} = 2.0\text{ V}$	—	600	mV
Input Voltage	Logic 1	$V_{IN(1)}$ or $V_{EN(1)}$	2.0	—	V
	Logic 0	$V_{IN(0)}$ or $V_{EN(0)}$	—	0.8	V
Input Current	Logic 1	$V_{IN(1)}$ or $V_{EN(1)} = 2.0\text{ V}$	—	20	$\mu\text{A}$
	Logic 0	$V_{IN(0)}$ or $V_{EN(0)} = 0.8\text{ V}$	—	-10	$\mu\text{A}$
Total Supply Current	$I_{CC}$	$I_{OUT} = 700\text{ mA}^*, V_{IN}^\dagger = V_{EN} = 2.0\text{ V}$	—	65	mA
		Outputs Open, $V_{IN}^\dagger = 0.8\text{ V}, V_{EN} = 2.0\text{ V}$	—	15	mA
Clamp Diode Forward Voltage	$V_F$	$I_F = 1.0\text{ A}$	—	1.6	V
		$I_F = 1.5\text{ A}$	—	2.0	V
Clamp Diode Leakage Current	$I_R$	$V_R = 60\text{ V}, V_{IN} = V_{EN} = 2.0\text{ V},$ $D_1 + D_2$ or $D_3 + D_4$	—	50	$\mu\text{A}$

\* Pulse test, allowable package power dissipation will be exceeded at increased ambient temperatures.

† All inputs simultaneously, all other tests are performed with each input tested separately.

# 2543 PROTECTED QUAD POWER DRIVERS

## TYPICAL OUTPUT BEHAVIOR



Dwg. No. WP-013-1

## CIRCUIT DESCRIPTION AND APPLICATION

### INCANDESCENT LAMP DRIVER

For incandescent lamp applications, the UDx2549B/EB or UDx2559B/EB, with improved shortcircuit protection and thermal limiting, are recommended.

### INDUCTIVE LOAD DRIVER

Bifilar (unipolar) stepper motors, relays, or solenoids can be driven directly. The internal flyback diodes prevent damage to the output transistors by suppressing the high-voltage spikes that occur when turning OFF an inductive load. For rapid current decay (fast turn-OFF speeds), the use of Zener diodes will raise the flyback voltage and improve performance. However, the peak voltage must not exceed the specified minimum sustaining voltage ( $V_{\text{SUPPLY}} + V_Z + V_F \leq V_{\text{OUT(SUS)}}$ ).

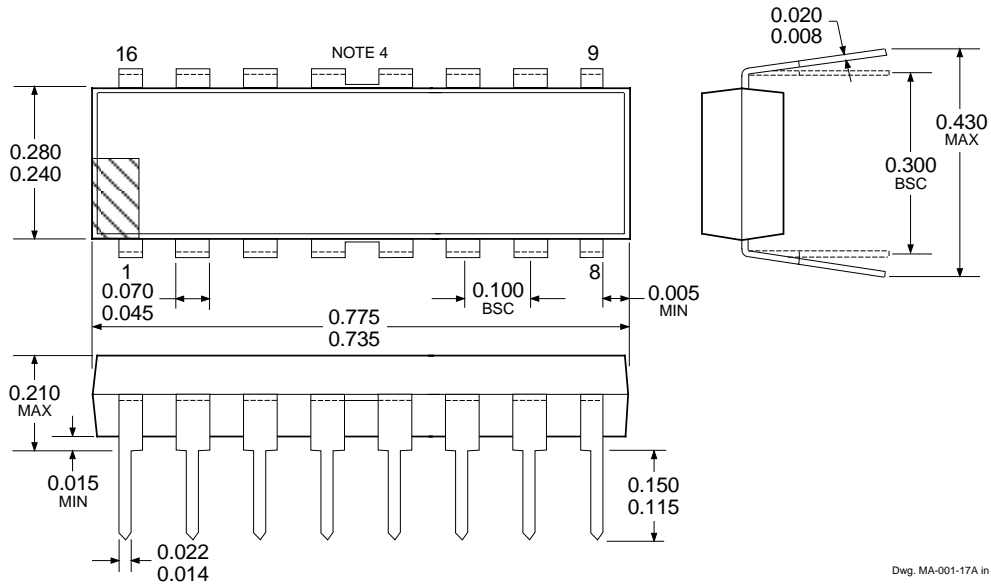
### FAULT CONDITIONS

In the event of a shorted load, the load current will attempt to increase. As described above, the drive current to the affected output stage is diverted, causing the output stage to go linear, limiting the peak output current to approximately 1 A. As the power dissipation of that output stage increases, a thermal gradient sensing circuit will become operational, further decreasing the drive current to the affected output stage and reducing the output current to a value dependent on supply voltage ( $I_{\text{OUT}} \approx 2.4/V_{\text{SUPPLY}}$ ). If the fault condition is corrected, the output stage will return to its normal saturated condition.

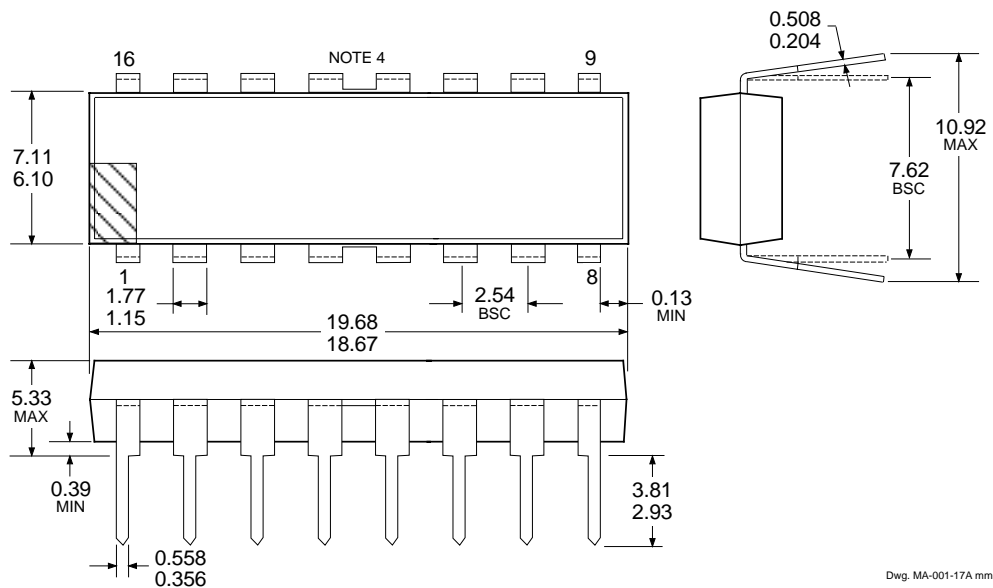
Due to the independent operation of the four channels, only a single channel should be shorted at a time. Multiple overload conditions may be tolerated provided rated package power dissipation is not exceeded.

# 2543 PROTECTED QUAD POWER DRIVERS

## UDN2543B and UDQ2543B Dimensions in Inches



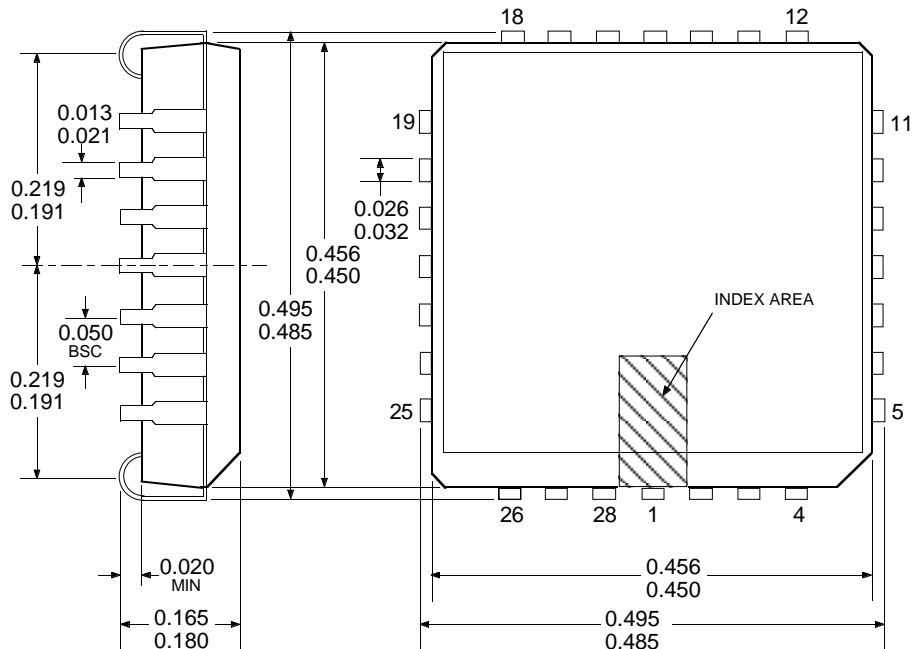
## Dimensions in Millimeters (Based on 1" = 25.4 mm)



- NOTES:
- Exact body and lead configuration at vendor's option within limits shown.
  - Lead spacing tolerance is non-cumulative
  - Lead thickness is measured at seating plane or below.
  - Webbed lead frame. Leads 4, 5, 12, and 13 are internally one piece.

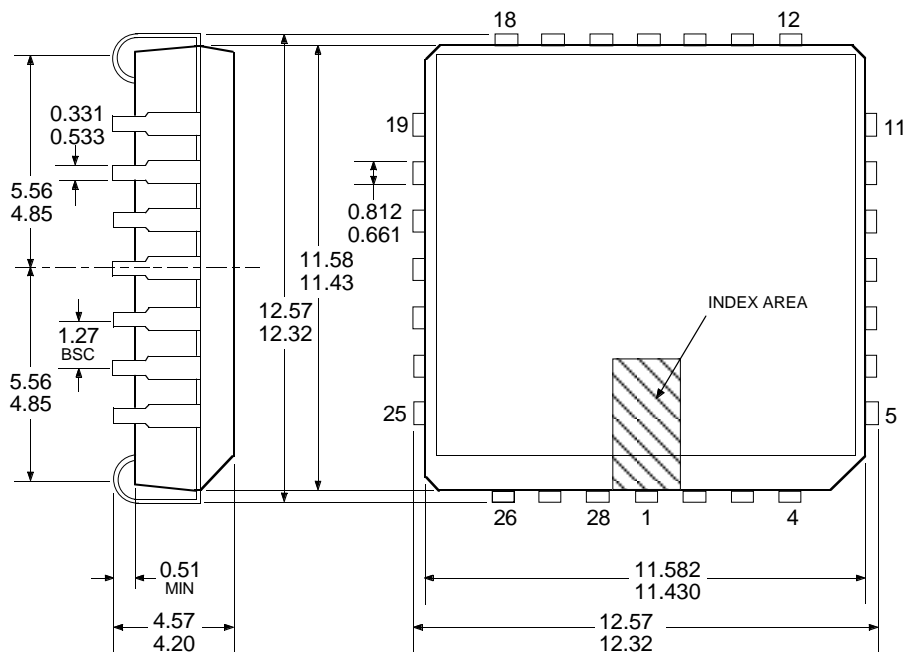
# 2543 PROTECTED QUAD POWER DRIVERS

## UDN2543EB and UDQ2543EB Dimensions in Inches



Dwg. MA-005-28A in

## Dimensions in Millimeters (Based on 1" = 25.4 mm)



Dwg. MA-005-28A mm

- NOTES: 1. Exact body and lead configuration at vendor's option within limits shown.  
2. Lead spacing tolerance is non-cumulative  
3. Webbed lead frame. Leads 5 through 11 and 19 through 25 are internally one piece.

**2543**  
***PROTECTED***  
***QUAD POWER DRIVERS***

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# 2543 PROTECTED QUAD POWER DRIVERS

## POWER SINK DRIVERS SELECTION GUIDE

IN ORDER OF 1) OUTPUT CURRENT, 2) OUTPUT VOLTAGE, 3) NUMBER OF DRIVERS

Output Ratings *			Features					Part Number †
mA	V	#	Serial Input	Latched Drivers	Diode Clamp	Saturated Outputs	Internal Protection	
100	20	8	–	–	–	X	–	2595
	30	32	X	X	–	–	–	5833
	40	32	X	X	–	X	–	5832
250	150	7	–	–	X	–	–	7003
300	45	1		Hall Sensor/Driver	X	–	X	5140
	50	8	–	–	X	X	–	2596
	60	2		Hall Sensor/Driver	–	X	–	5275
	80	2	–	–	X	X	–	5713
	80	4	–	–	X	X	–	5703 and 5706
350	50	4	–	X	X	–	–	5800
	50	8	–	X	X	–	–	5801
	50	8	X	X	–	–	–	5821
	50	8	X	X	X	–	–	5841
	80	8	X	X	X	–	–	5842
450	30	28	Dual 4 to 14-Line Decoder/Driver			–	–	5817
600	60	4	–	–	–	X	X	2547
	60	4	–	–	X	X	X	2549
700	60	4	–	–	X	X	X	2543 and 2559
750	50	8	–	–	X	X	–	2597
900	14	2		Hall Sensor/Driver	X	X	X	3625
	26	2		Hall Sensor/Driver	X	X	X	3626
1000	46	4	Stepper Motor Controller/Driver			MOS	–	7024 and 7029
1200	46	4	Microstepping Controller/Driver			MOS	–	7042
1250	50	4	Stepper Motor Translator/Driver			–	X	5804
	50	4	–	–	X	–	–	2064 and 2068
1500	80	4	–	–	X	–	–	2065 and 2069
1600	50	9	X	X	–	–	X	5829
1800	50	4	–	–	X	–	–	2544
	50	4	–	–	X	–	–	2540
3000	46	4	Stepper Motor Controller/Driver			MOS	–	7026
4000	50	4	–	–	X	–	–	2878
	80	4	–	–	X	–	–	2879

\* Current is maximum specified test condition, voltage is maximum rating. See specification for sustaining voltage limits or over-current protection voltage limits.

† Complete part number includes additional characters to indicate operating temperature range and package style.

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